



play alone, play along

*probo-t*  
2208



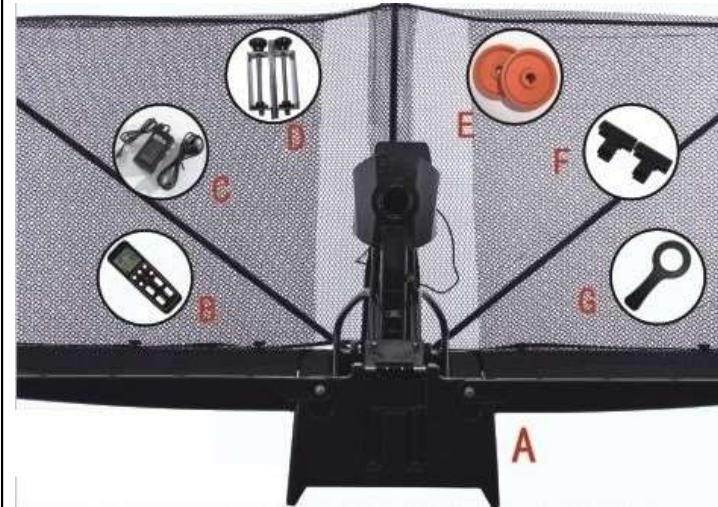
### Technical Parameters

Gross Weight	9 Kgs
Net Weight	5.5 Kgs
Package Dimensions	L88 X W41 X H40 cms
Rated Voltage/Power/Frequency	220-240V/50W/50/60Hz

### Functional Parameters

Spin	Top Spin, Left Spin, Under Spin, Side Spin, No Spin
Angle	Adjustable
Oscillation	Fix and Controllable by Wireless Remote Control
Auto Feeder	Metal Tray collects the balls and automatically feeds the balls to the robot
Serving Frequency	30-90 Balls/minute
Serving Speed	4-40 mts/sec
Point of Fall	Adjustable - Fixed, Random
Operation Method	2.4G Wireless Remote Control

### Standard Accessories



### Installation

#### Step 1 Unpack the Box



#### Step 2 Spread out the Integrated Tray/Ball Collection Net



**Step 3 Use the Iron Support Bars to extend the spread of the Net**



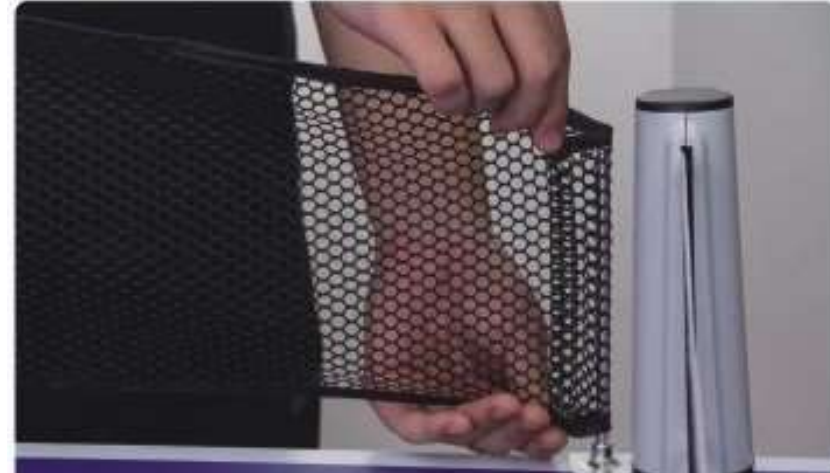
**Step 4 The spread out Net should be as depicted in the picture**



**Step 5 Hold the Robot from behind with the two integrated support bars spread out and fix it to the TT Table**



**Step 6 Attach the Net bars to the TT Table and insert the endings of the Net into the Net Bars**



**Step 7 Insert the adaptor cable in the socket provided at the back of the TT Robot**

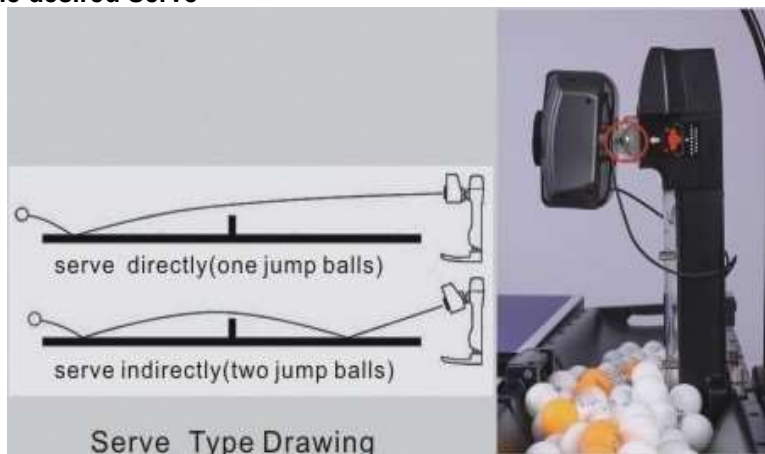


**Step 8 You are ready to go**



**Serve Types**

**Adjust the angle using the screw shown in the image to achieve the desired Serve**



**Adjusting the Spin**

Rotate the Serving Head manually to achieve the desired Spin



## Troubleshooting

Fault phenomenon	Failure cause	Treating method
Plug in with no reaction	Power failure	Replace power
	Not well plug in	Re-plug in
Balls are not out	No balls in recovery trough	Push balls into the middle to push balls out
	Balls are broken,dirty or not standard	Replace standard 40MM/40+ new balls
	Motor of serving ball is broken	Replace
	Gear of serving ball is broken	Replace
Serve ball weakly	Topsin or underspin value is too low	Increase the upspin or underspin value
	Motor of serving ball is broken	Replace
	Power is not well connected	Re-plug
	Line of serving ball motor is disconnected	Re-plug
NO oscillation	Remote control oscillation not turned on	Increase oscillation value
	Motor of oscillation is broken	Replace
	Oscillation gear box is broken	Replace
	Power is not well connected	Re-plug
	Oscillation motor is disconnected	Re-plug
remote control failure	Low battery	Replace new battery

## Best Practices

Rev up the Main Engine for 2-4 minutes before you put it to use.

Use ONLY standard 40 mm or 40+ balls. Avoid using soft balls. Usage of soft balls could result in balls getting stuck inside the robot. For Best results, use Sports Ami 40+ 1 star balls.

Balls should always be cleaned and dried. Avoid dust getting onto the balls as this may result in balls getting clamped

The robot must be used only under the guidance of adult or experienced supervisor

Keep the balls inside the Storage Tub even when not in use

If the robot is not in use for a long time, it is highly advised that it should be properly bagged, to avoid dust. As a good practice, always cover the robot to avoid dust

Proper and timely cleaning of balls and the robot itself could lead to better results and long life

## Replacing the Motor/Wheel - I



In the case that the serving ball wheel is damaged or out of shape,might you need to exchange the wheel.

## Replacing the Motor/Wheel - II

- (1). Check which serving ball wheel is damaged. Then remove the cover on both sides of the table tennis robot head and replace it.


- (2). If it is necessary to replace up serving ball wheel, use a screwdriver to remove the screw.


- (3). Disassemble the screw from the serving wheel, take out the damaged wheel.


- (4). Take a new wheel, and put it inside follow the process before.



# *Sports Ami*

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