

WARNING

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Hi5 Controller Function Manual

Scheduling Grease Filling Ver.3









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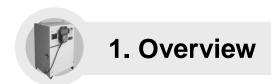
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1.1. About Scheduling of Grease Filling

The scheduling is a function to send a signal at the time of grease filling, based on the reference distances of the filling and regular replacement cycle of the grease provided on a basis of the makers of grease filling elements comprising each axis of a robot. For this function, the robot informs the users of the time of grease filling in the form of the controller output signal, alarm output (W0018), and state Icon output by calculating the total distance and by setting the regular filling time for each element.







2.1. Scheduling Grease Filling

The scheduling of grease filling is set on $[System] \rightarrow [3: Robot Parameter] \rightarrow [11: Scheduling of Grease Filling].$



Reference Distance (m or rad): Monitoring

The reference distances of grease filling are set for each element.

Amount of Grease Filling (cc): Monitoring

Among elements, the LM Block and Rack & Pinion display the amount of grease filling per block and meter, respectively.

Distance (m or rad): Monitoring & Setting

- ① The total distance may be monitored (displayed in meters or rad).
- ② After filling grease, make sure to set the distance of the involved element to zero (0).

• Reference Distance Detection Ratio (%): Setting

- ① Set the reference distance detection ratio. For example, if the reference distance is 100 meters and the detection ration is 80 %, 80 meters are detected as a reference distance.
- ② If the reference distance detection ratio (%) is zero (0), invalidate the detection of the grease filling time for the involved element.

Setting Time (Day): Monitoring & Setting

Set the regular detection time. For example, if the remaining date is set to ten (10) days, the date gets counted down, and the alarm and signal are output ten (10) days later.

- In the case of P8 and AP2 robots of LG Display co., Ltd., the initial set value of grease filling time is three (3) months or 90 days.
- With respect to robot models in the auto industry, the alarm and signal are not output due
 to a lack of current database. However, the regular filling time is temporarily set to 850
 days based on 20,000 hours. Formal data are expected to be registered after the data
 have been secured afterwards.

2.2. Setting Alarm of Grease Filling

Set a signal that outputs the required grease filling time outwards on "System" \rightarrow "2: Control Parameter" \rightarrow "2: Setting I/O Signal" \rightarrow "4: Allocating Output Signal".



The initial set value is zero (0). It shall be set so that the signal is output outwards. (Note: The allocated signal of grease filling is FB5.DO78)



2.3. Monitoring Grease Filling

Signal Output

Set a monitoring screen of the output signal set on "Service" \rightarrow "1: Monitoring" \rightarrow "2: I/O Signal". When the signal is allocated, it is displayed in bold. When the conditions of signal output are met, it displayed in yellow. (Make sure of # 9 on the Universal Output Signal Monitoring Window as shown in the following figure.)

Grease Filling Icon Output

The Icon is displayed in order to signal the grease filing alarm to the left side of "Teach/Playback" mode marks on the teaching pendant. The Icon is flickering (blinking) at the time of greasing filling.

Distance (%)

The total distance of each current part is the value set on "System" \rightarrow "3: Robot Parameter" \rightarrow "11: Setting Greasing Filling Time", converted into a percentage. When the total distance is 80 % and over, it is displayed in yellow; when the total distance is 100 %, it is in red.



Remaining date

The value, which has been set on "System" \rightarrow "3: Robot Parameter" \rightarrow "11: Scheduling Grease Filling", indicates the remaining date of the current element. Input the next filling schedule after the filling has been completed. When the remaining days are less than ten (10) days, it is displayed in yellow; when the remaining days are within five (5) days, it is displayed in red.



Referenc

- 1 If the total distance detection ratio of each part of a robot is over the set value, the warning messages (W0018 grease filling needed! Make sure of the System Feature Data/Distance), signals, and Icon are sent outwards and on T/P screen. At this time, the robot continues to run automatically.
- ② Even when the total distance was not cleared ("0"), automatic operation is possible, and the signals and Icon continue to be sent outwards and on T/P screen.
- When the control power is on again in the aforementioned conditions, the alarm is always sounded.





2.4. Solution Procedure When the Grease Filling Alarm Is Sounded

W0018 Grease Filling Needed! WARNING



Verify the part which needs grease filling on the "System Feature Data/Distance."



The user stops the robot



Fill grease to the part where the alarm has been sounded



Initialize the detection date and distance of the part that has completed filling on the "System \rightarrow "3: Robot Parameter \rightarrow "11: Scheduling Grease Filling \rightarrow ".

• The time when the user stops the robot depends on the user's judgment.

2.5. Model Elements for Grease Filling and Filling Data

(1) Standards of the P8 LCD Robot for Returning

Grease Filling Elements		HC2500B2D-3900-10 HC2500B2D_3000_10 (X, TH, Z1, Z2, L, R)		HC2500B2D-3900-00 (TH, Z1, Z2, L, R)		HC2500B2S_3000_10 HC2500B2S_3900_10 (X, TH, Z1, Z2, L)		
		Filling distance (m or rad)	Filling amount (CC)	Filling distance (m or rad)	Filling amount (CC)	Filling distance (m or rad)	Filling amount (CC)	
X	X1	LM Block	1,000,000	(per block)			1,000,000	(per block)
	X2	Rack & Pinion	1,000,000	100 (per meter)			1,000,000	100 (per meter)
тн	TH1	RV decelerator	471,239	4500	471,239	4500	471,239	4500
Z1	Z11	LM Block	1,000,000	8.5 (per block)	1,000,000	8.5 (per block)	1,000,000	8.5 (per block)
	Z12	Ball screw	1,000,000	12	1,000,000	12	1,000,000	12
Z2	Z21	LM Block	1,000,000	8.5 (per block)	1,000,000	8.5 (per block)	1,000,000	8.5 (per block)
	Z22	Ball screw	1,000,000	VY IN ₂₀	1,000,000	S CO ₂₀ L	1,000,000	20
	L1	RV decelerator	942,478	1500	942,478	1500	942,478	1500
L	L2	RV decelerator	1,884,956	1200	1,884,956	1200	1,884,956	1200
	L3	RV decelerator	942,478	900	942,478	900	942,478	1000
	R1	RV decelerator	942,478	1500	942,478	1500		
R	R2	RV decelerator	1,884,956	1200	1,884,956	1200		
	R3	RV decelerator	942,478	900	942,478	900		



Grease Filling Elements		HC2500B2S_3000_00 HC2500B2S_3900_00 (TH, Z1, Z2, L)		HC2500B1D_1700_10 (X, TH, Z1, L, R)		HC2500B1S_1700_10 (X, TH, Z1, L)		
		Filling distance (m or rad)	Filling amount (CC)	Filling distance (m or rad)	Filling amount (CC)	Filling distance (m or rad)	Filling amount (CC)	
X X1 I		LM Block			1,000,000	(per block)	1,000,000	22 (per block)
^	X2	Rack & Pinion			1,000,000	100 (per meter)	1,000,000	100 (per meter)
тн	TH1	RV decelerator	471,239	4500	471,239	4500	471,239	4500
Z 1	Z11	LM Block	1,000,000	8.5 (per block)	1,000,000	8.5 (per block)	1,000,000	8.5 (per block)
	Z12	Ball screw	1,000,000	12	1,000,000	12	1,000,000	12
Z21		LM Block	1,000,000	8.5 (per block)				
Z2	Z22	Ball screw	1,000,000	20				
	L1	RV decelerator	942,478	1500	942,478	1500	942,478	1500
L	L2	RV decelerator	1,884,956	1200	1,884,956	1200	1,884,956	1200
	L3	RV decelerator	942,478	900	942,478	900	942,478	900
R	R1	RV decelerator			942,478	1500		
	R2	RV decelerator			1,884,956	1200		
	R3	RV decelerator			942,478	900		



(2) Standards of the AP2 LCD Robot for Returning

Grease Filling Elements		HC920C2 (X, Z		HC920C2D-900-00 (Z1, Z2)		
		Filling distance (m or rad)	Filling amount (CC)	Filling distance (m or rad)	Filling amount (CC)	
Х	X1	LM Block	100,000	4.2 (per block)		
Z 1	Z11	LM Block	100,000	2 (per block)	100,000	2 (per block)
21	Z12	Ball screw				
Z2	Z21	LM Block	100,000	1.4 (per block)	100,000	1.4 (per block)

			HC920B1	D-1600-10	HC920B1D-1600-00	
			HC920B1	D-2400-10	HC920B1D-2400-00	
Grease Filling Elements		(X, TI	H, Z1)	(TH, Z1)		
	rease Filling El	ements	Filling Filling		Filling	Filling
			distance	amount	distance	amount
			(m or rad)	(CC)	(m or rad)	(CC)
х	X1	LM Block	100,000	5.2 (per block)		
^	ХЗ	Rack & Pinion	100,000	100 (per meter)		
тн	TH1	RV decelerator	942,478	1500	942,478	1500
Z1 ·	Z 11	LM Block	100,000	3.2 (per block)	100,000	8.5 (per block)
	Z 13	Rack & Pinion	100,000	100	100,000	100





Head Office

Tel. 82-52-202-7901 / Fax. 82-52-202-7900 1, Jeonha-dong, Dong-gu, Ulsan, Korea

A/S Center

Tel. 82-52-202-5041 / Fax. 82-52-202-7960

Seoul Office

Tel.82-2-746-4711 / Fax. 82-2-746-4720 140-2, Gye-dong, Jongno-gu, Seoul, Korea

Ansan Office

Tel.82-31-409-4945 / Fax.82-31-409-4946 1431-2, Sa-dong, Sangnok-gu, Ansan-si, Gyeonggi-do, Korea

Cheonan Office

Tel.82-41-576-4294 / Fax.82-41-576-4296 355-15, Daga-dong, Cheonan-si, Chungcheongnam-do, Korea

Daegu Office

Tel.82-53-746-6232 / Fax.82-53-746-6231 223-5, Beomeo 2-dong, Suseong-gu, Daegu, Korea

Gwangju Office

Tel. 82-62-363-5272 / Fax. 82-62-363-5273 415-2, Nongseong-dong, Seo-gu, Gwangju, Korea

HEAVY INDUSTRIES CO., LTD.

• 본사

Tel. 052-202-7901 / Fax. 052-202-7900 울산광역시 동구 전하동 1 번지

• A/S 센터

Tel. 82-52-202-5041 / Fax. 82-52-202-7960

• 서울 사무소

Tel. 02-746-4711 / Fax. 02-746-4720 서울특별시 종로구 계동 140-2 번지

• 안산 사무소

Tel. 031-409-4945 / Fax. 031-409-4946 경기도 안산시 상록구 사동 1431-2 번지

• 천안 사무소

Tel. 041-576-4294 / Fax. 041-576-4296 충남 천안시 다가동 355-15 번지

• 대구 사무소

Tel. 053-746-6232 / Fax. 053-746-6231 대구광역시 수성구 범어 2 동 223-5 번지

• 광주 사무소

Tel. 062-363-5272 / Fax. 062-363-5273 광주광역시 서구 농성동 415-2 번지